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(BPE)

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Markov Chain Order Estimation to the Weather State of Mosul City by Using Backpropagation Network

ABSTRACT

The operation of order estimation of a Markov chain to represent the observation chain is an important problem in realistic applications. One method of order estimation depending on intelligence technicality is represented by artificial neural networks . in this research we design an artificial neural network which is the backpropagation error (BPE) .

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2010/ 4/28 :

2010/ 1/ 19:

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 This research treated realistic problem in Markov chain order estimation to the weather state of raining months in Nineveh Governorate (clearly, cloudy, rainy) , and a special algorithm has been prepared for training the network .We suggest another neural network for backpropagation error which is forecasting the weather state , which is designed depending on the past network after modify it.

المقدمة Introduction

Markov Order Estimation

Chain

X_{n-1} X_n

[3][4][2]

$$\begin{aligned}
 & [1][5]-: \quad X_{n-1} \quad X_n \\
 & \Pr[X_n=i \mid X_{n-1}=j, X_{n-2}=j_1, \dots] \\
 & = \Pr[X_n=i \mid X_{n-1}=j]
 \end{aligned}$$

Second Order Markov Chain

$$\begin{aligned}
 & \Pr[X_n=i \mid X_{n-1}=j, X_{n-2}=j_1, X_{n-3}=j_2, \dots] \\
 & = \Pr[X_n=i \mid X_{n-1}=j, X_{n-2}=j_1] \\
 & : \quad k
 \end{aligned}$$

$$\begin{aligned}
 & \Pr[X_n=i \mid X_{n-1}=j, X_{n-2}=j_1, X_{n-3}=j_2, \dots] \\
 & = \Pr[X_n=i \mid X_{n-1}=j, X_{n-2}=j_1, X_{n-3}=j_2, \dots, X_{n-k}=j_k]
 \end{aligned}$$

()
 (2433) (1997-1987)
 A (80)

(Backpropagation Error Network BPE)

(Steps (Learning Rate η)
 Number)

(Perceptron)

[1].

Architecture Backpropagation Network

(Input Layer)
 (Output Layer) (Hidden Layer) ()
 (31)

...

(31) ()
 (5)
 A ()
 (1) C (0) B (-1)
 (31)
 (Supervised (target output) Learning)

(1)

(1)

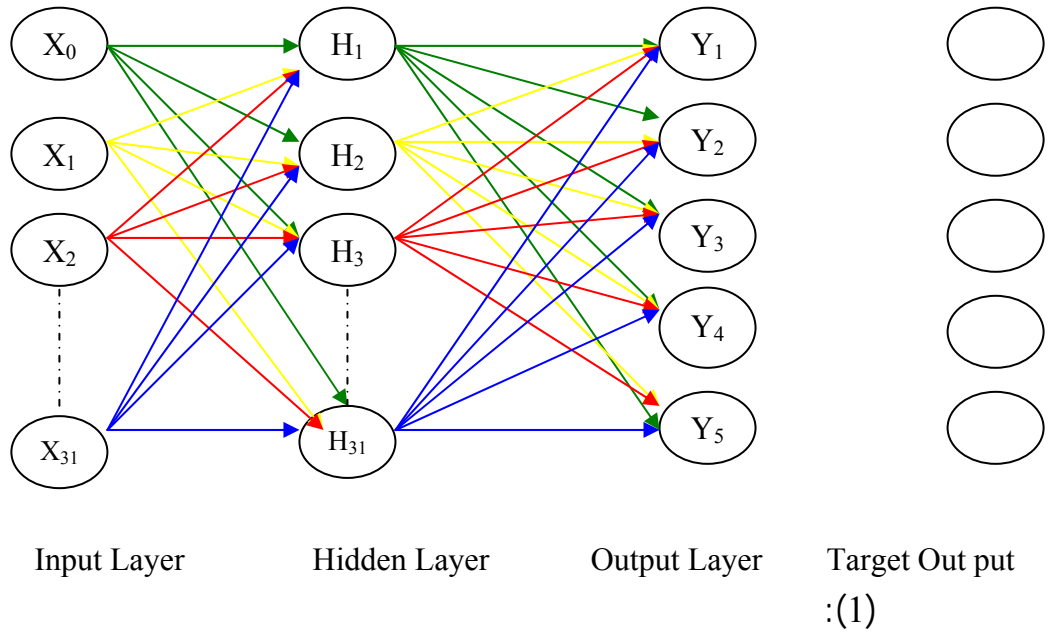
1	1	0	0	0	0
2	0	1	0	0	0
3	0	0	1	0	0
4	0	0	0	1	0
5	0	0	0	0	1

(1)

(1,0,0,0,0)

(1)

(1)



-:

$$.0 < \eta < 1 \quad \eta$$

-1

-2

-3

$$H_{jl} = w_{0i} + \sum x_i w_{ij}$$

: w

: I

: O

-4

$$H_{jo} = f(v_{0k} + H_{jl} v_{jk})$$

: v

...

$$y_{kl} = f(v_{0k} + \sum_{k=1} y_k v_{jk}) \quad -5$$

$$\delta_k = (y_t - y_k) f'(y_{kl}) \quad -6$$

:y_t:y_k

-7

$$\Delta v_{jk} = \eta \delta_k H_{jo} \quad -8$$

$$\Delta v_{0k} = \eta \delta_k \quad -9$$

$$\delta_j = \sum \delta_k v_{jk} f'(H_{jo}) \quad -10$$

$$\Delta w_{ij} = \eta \delta_j x_i \quad -11$$

$$\Delta w_{0j} = \eta \delta_j \quad -12$$

$$V_{jk(\text{new})} = V_{jk(\text{old})} + \Delta V_{jk} \quad -13$$

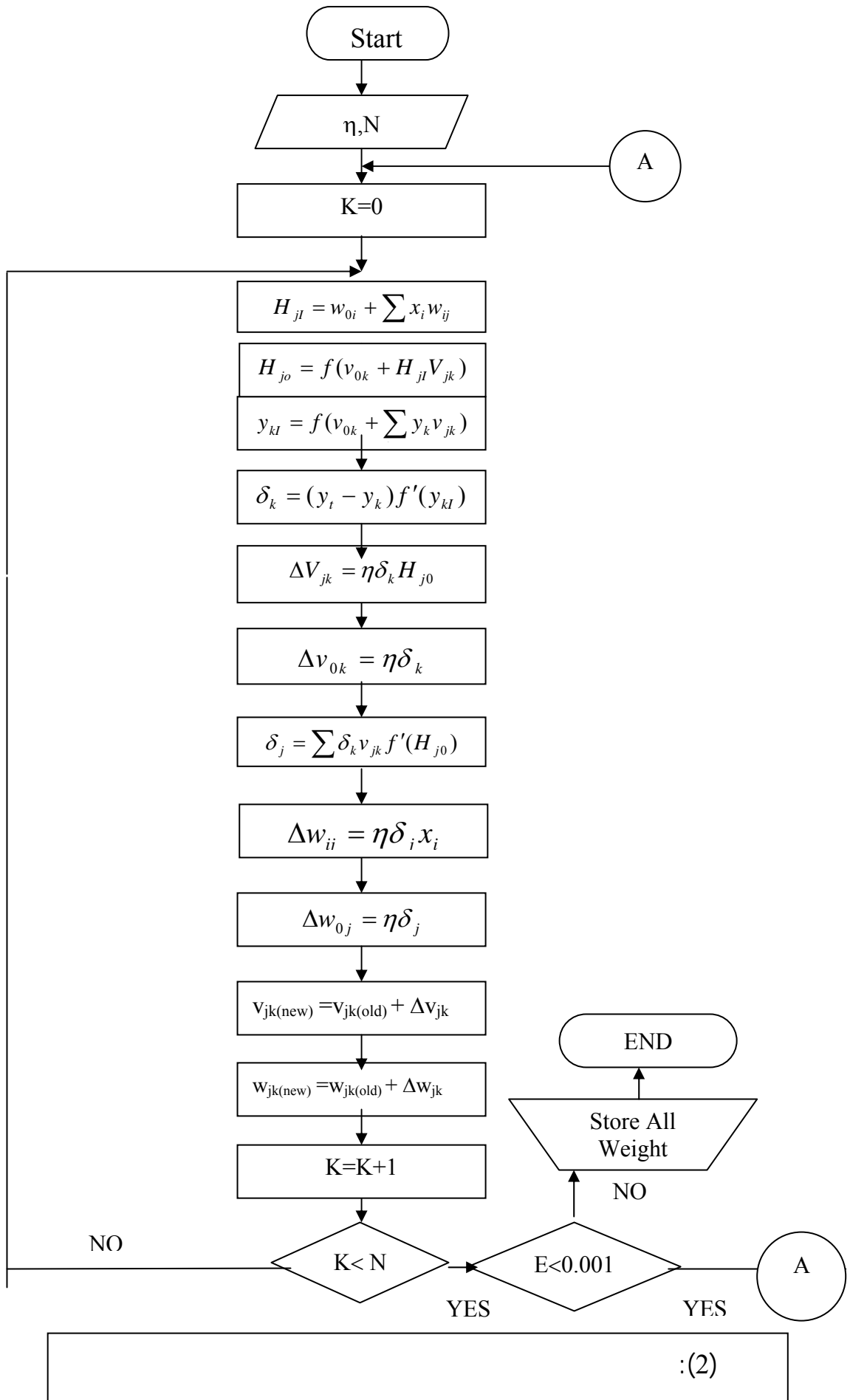
$$W_{jk(\text{new})} = W_{jk(\text{old})} + \Delta W_{jk} \quad -14$$

K=K+1 أضف للعداد

-15

. (0.001)

(2)



:(2)

(η)

Effect of Learning Rate on Steps Number of Training in the Backpropagation Error Network of Order Estimation

(Steps		(Learning Rate η)	
	$0 < \eta < 1$	(η)	Number)
(30)	(150)	(N)	
		(Iu)	
			(31)
(5)	(Ou)	(31) ()	(H)
(η)			
		(In)	0.001
		-: (2)	(η)

(η) : (2)

(N)	Iu	H	Ou	η	In
150	31	31	5	0.1	201
				0.2	86
				0.3	33
				0.4	22
				0.5	17
				0.6	15
				0.7	15
				0.8	15
				0.9	16
				0.95	18
				0.97	30
				0.99	50

(η)

(2)

(0.8 0.7 0.6)

. η=0.7

(η)

) η

(2)

(

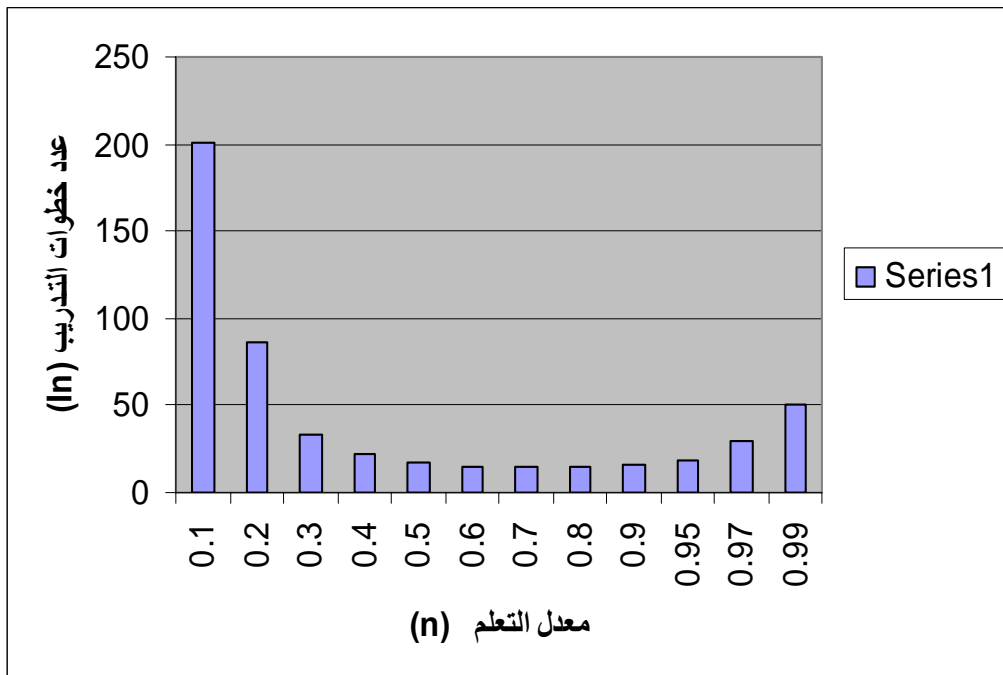
η

(3)

η

-: In

η



(In)

η

: (3)

[2] [1]-:

$$H = E(-\log_2 p)$$

$$= - \sum P(j) \log_2 p(j)$$

(1-5)

(η=0.7)

(150)

(15)

(0.10)

(0)

(0.06)

(0.68)

(0.08)

: (4)

(0.88)

-:

Iter = 15 neta = +0.70 No of Chain = 150

+0.00	+0.00	+0.10	+0.00	+0.06	BAAAAABABAAACCCBBBCCBCBBCCCCDD
+0.08	+0.00	+0.00	+0.68	+0.88	BCBAABACABAACCBCCBBBCBABBAAAAAA
+0.00	+0.00	+0.00	+0.52	+0.36	BBABACCCCCCCCCBABBABBBAAAAAAAD
+0.00	+0.00	+0.82	+0.58	+0.00	CCBABCBBBCBCCCCCCCCCCCCCCCC
+0.00	+0.00	+0.96	+0.04	+0.00	CABBCBBBCCCBCCCBCCCBCCCBCCCBCC
+0.00	+0.00	+0.96	+0.21	+0.00	CBAABCBBCCBCCBAABBBBCCCCCCCCDD
+0.00	+0.00	+0.02	+0.45	+0.00	CCCCABACBBACCACCAAABAABBCCCCCCC
+0.00	+0.00	+0.47	+0.38	+0.00	CBABACCBABCBBBCCBBCCCCCCCCCCCC
+0.00	+0.00	+0.05	+0.24	+0.00	ABACCCCB BBBCCCBCCCBCCCBCCCBCCDD
+0.00	+0.92	+1.00	+0.00	+0.00	BBBACABACBBBABABABCABBBCCBBCCCC
+0.00	+0.00	+0.60	+0.20	+0.00	CBACBBCCBBBCCCCCBCCCBCCBBBCCDD
+0.00	+0.00	+0.77	+0.01	+0.00	CBABBBBBBBBCCCCCCCCCCCCCCCCCCCC
+0.00	+0.00	+0.94	+0.02	+0.00	BBBBBBBBBCCCCCCCCCCCCCCCCCCCCCCCC
+0.01	+0.00	+0.89	+0.11	+0.00	CCBABAABBCCBCBBBCCCCCB BBBBBD
+0.00	+0.02	+0.48	+0.02	+0.00	ACCBAABAACCCABAACCAACCCCCCCCCC
+0.00	+0.00	+0.00	+0.99	+0.00	CCCCCCCCBABBACCCCCCCCCACCAACAAA
+0.00	+0.00	+0.00	+0.06	+0.89	CBCCCCABCCCCCAABBABAAAAAAADDD
+0.00	+0.00	+0.06	+0.09	+0.00	BAACBAACBCCBCCCCCCCCCCCCCCCCCCCC
+0.00	+0.00	+0.01	+0.97	+0.00	CCABABABBACCCBCCBCCCBCCBCCBBCCD
+0.00	+0.00	+1.00	+0.01	+0.00	CCCCBBACCCCBCCBACCCCCCCCCCCCCCC
+0.00	+0.00	+0.01	+0.66	+0.00	CBBCBCCBBBCCBBCCCCCCCCCCCCCCCC
+0.00	+0.00	+0.75	+0.04	+0.00	CCABABBBBBBCCCCCCCCCCCCCCCCCCCCD
+0.00	+0.00	+1.00	+0.00	+0.00	CCCCBBABABBACCCBABACCACAACCCCC
+0.02	+0.00	+0.58	+0.00	+0.00	ABAABBABBBACCCCBCCBABAACCCACCC
+0.00	+0.00	+0.01	+0.74	+0.00	BABABBACCCCBCCBABAABBCBCCDDDD
+0.93	+0.00	+0.00	+0.11	+0.00	ABABAAABABBAAAAACCCCCACCBBAACC

+0.00	+0.00	+0.03	+0.06	+0.00	CACCAAACCBBCBCCBCCBCCBCCBCCBCCD
+0.00	+0.00	+0.76	+0.00	+0.00	CBBACBCABABCCCCCCCCCCCCCCCC
+0.00	+0.00	+0.08	+0.34	+0.00	CCCBCCCCBBABCCBBBCCCBCCCCC
+0.00	+0.00	+0.87	+0.02	+0.00	CBAABACCCCCBBABABCCCCCCCCC
+0.00	+0.00	+0.00	+0.94	+0.00	CCBABBACCBAAACCBABAACCCCCAAA
+0.00	+0.00	+0.01	+0.66	+0.23	CCCCCACCCCCCCCCCACCCAAAAAAA
+0.10	+0.12	+0.02	+0.00	+0.01	ACCCCCCABABAABABABABAAAAAAD
+0.00	+0.00	+0.05	+0.06	+0.00	BABAACCCCCCCCCCCCCCCCCCCCC
+0.00	+0.00	+0.04	+0.03	+0.00	BAABCACCBAAABBBCCCCCCCCCCCC
+0.00	+0.21	+0.10	+0.01	+0.00	BABAAAABCBCBCCBBBCCBBBCCCC
+0.00	+0.00	+0.20	+0.26	+0.00	CCCCBBBCCCCCCCCCCCCCCCCCCC
+0.28	+0.00	+0.70	+0.06	+0.00	CCCBBAABBBBBAACABCCACCCCCC
+0.00	+0.97	+0.00	+0.00	+0.00	AACBABACBBABABABACCCAACACBB
+0.64	+0.00	+0.00	+0.99	+0.00	CCABABABAACCCABACCCCCCCCCCA
+0.00	+0.00	+0.00	+0.25	+0.00	AAAABACCBCCCCBACCACCCCCCDD
+0.00	+0.00	+0.00	+0.26	+0.00	CCCBACBAABBCCCCCCCCCCCCCCCC
+0.04	+0.00	+0.08	+0.06	+0.00	ACBCACCCCCBBBBAABAABAACCBCC
+0.01	+0.69	+0.00	+0.62	+0.00	ABCBACCBABACABABBCABABCCCBB
+0.00	+0.00	+0.55	+0.02	+0.00	CCCBACCBCCCCBBBCBCCCCCCCCCCC
+0.00	+0.00	+0.00	+0.04	+0.00	AAABABBCCCCCCBAABBBBCCCCC
+0.00	+0.05	+0.01	+0.00	+0.00	BACCBABABBABCAAACCCAACABCCCC
+0.00	+0.00	+0.01	+0.02	+0.00	BAAABBAABCBAACAABCCCCCCCCCCC
+0.00	+0.00	+0.00	+0.05	+0.00	CACBACCBAAABABBCBCCCBCCBBDD
+0.02	+0.00	+0.00	+0.02	+0.10	AABCCCCAABCCCBCCCCCBABABAABB
+0.00	+0.00	+0.35	+0.00	+0.01	BAAABCCABAACCCCCCCCCBBBCCCC
+0.00	+0.00	+0.28	+0.00	+0.00	CCCAAABBCBCCCCCCCCBCCCCCCCC
+0.00	+0.00	+0.42	+0.00	+0.00	BCCBBABBBBCCCCCCCCB BBBBCCCC
+0.00	+0.00	+0.61	+0.00	+0.00	BCBBBBAAACABCCBBAACBABABCCCA
+0.01	+0.00	+0.07	+0.00	+0.00	ABCCBCBABACCCCBABABAAAACCCAAA
+0.00	+0.00	+0.00	+0.89	+0.40	CABCCACACCCCBABAAAAABBBBBBB
+0.00	+0.00	+0.13	+0.00	+0.01	ABBCAABABACCABCABACCCCCCDD
+0.00	+0.00	+0.13	+0.02	+0.00	CCCBCCCCBAAAAACCCBCCCCCCCCC
+0.00	+0.00	+0.06	+0.03	+0.43	CBACBAAABCCCCBBBCCBCCB BBBB
+0.00	+0.00	+0.06	+0.00	+0.00	ACCCBCCBBBCCBBBCCBCCCCCCCCC
+0.00	+0.00	+0.01	+0.26	+0.00	BBCBCCBCCCCCCCCCCCCCCCCCCCC
+0.00	+0.00	+0.01	+0.27	+0.00	BACCBACCCCCCCCCCCCCBBBCCCCC
+0.00	+0.00	+0.84	+0.00	+0.00	CCBACABAABBCBCCCCCCCCCCCCCCC
+0.00	+0.10	+0.00	+0.02	+0.00	CCCBBAACCAACACCBABAAAABABBAB
+0.00	+0.00	+0.34	+0.06	+0.00	CCBACBCCCCCBBAACCBCCB BBBB
+0.00	+0.15	+0.01	+0.00	+0.00	ABCCCCCBACAAAABBAABBBBBBBBB
+0.00	+0.00	+0.14	+0.12	+0.00	BCCBABAACBBBCCBCCCCBCCCCC
+0.00	+0.00	+0.04	+0.01	+0.00	CBACCCCCBABAABCCBCCBCCBCCCC

+0.00	+0.00	+0.00	+0.41	+0.00	CBCCBCCBBBBCCCCBCCCCCCCCCCCC
+0.00	+0.00	+0.51	+0.00	+0.00	ABBBABAACCCCCCCCCCCCCCCCCD
+0.01	+0.00	+0.68	+0.00	+0.00	ABBAABABAACCBABCBABACCBBBCCBBB
+0.00	+0.00	+0.02	+0.00	+0.00	ABBBBACCCCAABAABACCCCCCCCCCCC
+0.00	+0.00	+0.00	+0.02	+0.04	CCCB BBBBAACCBAAACCCCCCCCCDDD
+0.00	+0.00	+0.01	+0.00	+0.00	BAABACBACBACBAACCCBCABACCCBCC
+0.01	+0.00	+0.03	+0.00	+0.00	ABABBABBBCCCCCBBBACBACBBBBBBD
+0.00	+0.00	+0.05	+0.04	+0.00	BCCCCCBBCBBBBCCCBCCBCCCCCCCC

+2.19 +3.25 +19.78 +14.06 +3.42
1 7 39 24 5

: (4)

D

(1-5)

(4)

(2.19)

(3.25)

(14.06)

(19.78)

(4)

(3.42)

(39)

(5)

(7)

(24)

:

.()

(12)

()

(48)

)

(BPE)

.(

(Target

(Supervised Learning)

Output)

(A)

(1,0,0)

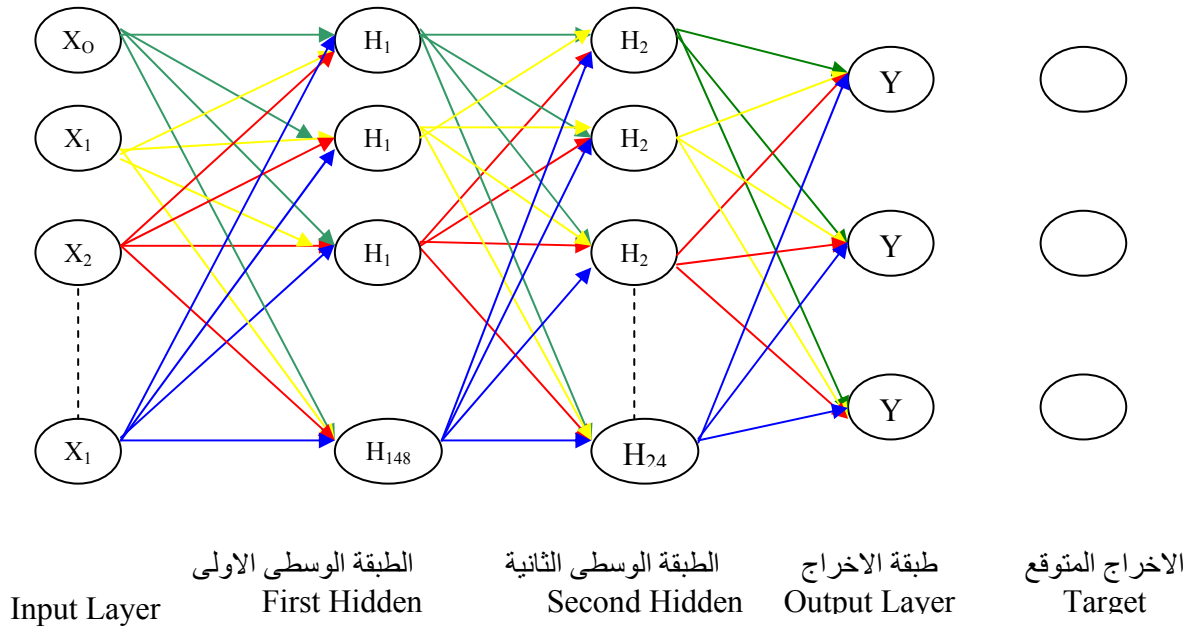
B

(0,1,0)

C

(0,0,1)

-(5)



:(5)

$$0.1 \leq \eta \leq 0.9 \quad (\eta) \quad (3)$$

(3)

η	Time(ms)
0.1	17.160000
0.2	7.865000
0.3	5.445000
0.4	12.705000
0.5	-
0.6	-
0.7	-
0.8	-
0.9	-

:

-:

$$.0 < \eta < 1$$

η

-1

-2

-3

$$H_{ihl} = w_{0i} + \sum x_i w_{ih}$$

: w_{ih}

: I

: O

-4

$$H_{hjl} = f(w_{0h} + \sum x_i w_{hj})$$

: w_{ih}

-5

$$H_{jo} = f(v_{0h} + H_{jl} v_{hj})$$

: v

- 6
- $$y_{jt} = f(v_{0j} + \sum_{k=1}^K y_j v_{kj})$$
- 7
- $$\delta_j = (y_t - y_j) f'(y_{jt})$$
- :y_t
- :y_j
- 8
- $$\Delta v_{hj} = \eta \delta_j H_{jo}$$
- 9
- $$\Delta v_{ih} = \eta \delta_j H_{ho}$$
- 10
- $$\Delta v_{0j} = \eta \delta_j$$
- 11
- $$\delta_h = \sum \delta_j v_{hj} f'(H_{ho})$$
- 12
- $$\Delta w_{hj} = \eta \delta_{hj} x_{hj}$$
- 13
- $$\Delta w_{0h} = \eta \delta_h$$
- 14
- $$v_{hj(\text{new})} = v_{hj(\text{old})} + \Delta v_{hj}$$
- 15
- $$w_{ih(\text{new})} = w_{ih(\text{old})} + \Delta w_{ih}$$
- 16
- الثانية
- $$w_{hj(\text{new})} = w_{hj(\text{old})} + \Delta w_{hj}$$
- 17 - أضيف للعداد K=K+1

...

[150]

-18

.(0.001)

(76)

($\eta = 0.3$)

(76)

(η

(76)

=0.3)

74

()

($\eta = 0.3$)

-: (6)

في ضوء ماورد في البحث نعرض اهم الاستنتاجات والتوصيات النظرية والعملية
بالآتي:

-:

-1

-2

-:

-1

-2

" : (2005)

-1

"

" : (2002) .

- -2

" DNA

" : (2000).

-3

(2000)

"

- 4- Finesso , L. (1991): "**Consistent Estimation of the Order for Markov and Hidden Markov Chain**" , Unpublished Ph. D . Thesis , Dept of Electrical Engineering , Harvard University.
- 5- Tong , H. ,(1975): "**Determination of the order of a Markov Chain by using Akaike's Information Criterion**" ,J. Ap.Prob.12 ,488-497.

الملحق A

سلسلة ماركوف للحالة الجوية اليومية للأشهر الماطرة في مدينة الموصل للفترة
1997-1987

BABABACCCCBACCCBBBCBBCCCCBCCCC
 BBACABACBACBCCCCCCCCCCCCCCCCD
 CCCBABABAACCCAAAAAAAAAAAAAAAAA
 BBABAAACCAAACCCCCCAAAAAAAAA
 BAAAAABABAAACCCBBBCBCCBCCCCDD
 BCBAABACABAACCBCCBBBCBABBAAAAA
 BBABACCCCCCBBABABBBAAAAAAAAAAD
 CCBABCCBBBCBCCCCCCCCCCCCCCCCC
 CABBCBBBCCCBCCCBCCBCCCCCCCCC
 CBAABCBBCCBCCBAABBBBCCCCCCCCD
 CCCABACBBACCACCAABAABBCCCCC
 CBABACCBABCBBCCBCCCCCCCCCCCCC
 ABACCCCBBBBCCCBCCCBCCBCCCCDD
 BBBACABACBBBABABABCABBBCCBCCCC
 CBBACBBCCBBBCCCCCBBCCCBBBBCCD
 CBABBBBBBBBCCCCCCCCCCCCCCCCC
 BBBBBBBBBBCCCCCCCCCCCCCCCCC
 CCBABAABBCCBCBBBCCCCCBBBBBBBD
 ACCBAABAACCCABAACCAACCCCCCCCC
 CCCCCCBABABACCCCCCACCACAAA
 CBCCCCABBCCCCAABBABAAAAAADDD
 BAACBAACBCCBCCCCCCCCCCCCCCCCC
 CCABABABBACCCBCCBCCBCBCCBBCCD
 CCCCCBACCBBCCBACCCCCCCCCCCCC
 CBBCBCCBBBCCBCCCCCCCCCCCCCCCC
 CCABABBBBBBCCCCCCCCCCCCCCCCD
 CCCCCBBABABBACCCBABACCACAACCCC
 ABAABBABBACACCCBCBABAACCCACCC
 BABABBACCCCCBCCABAABBCCBCCDDD
 ABABAAABABBAAAACCCCCACCBBAACC
 CACCAAACCBCCBCCBCCBCCBCCBCCD

CBBACBCABABCCCCCCCCCCCCCCCCCCCC
CCCBCCCCBBABCCBBBBCCCCBCCCCCCCC
CBAABACCCCCBBABABCCCCCCCCCCCCD
CCBABBACCBAAACCBABAACCCCCCAAAAA
CCCCCACCACCCCCCCCCACCCAAAAAAA
ACCCCCCABABAABABABABAAAAAAADD
BABAACCCCCCCCCCCCCCCCCCCCCCCCC
BAABCACCBAAABBBCCCCCCCCCCCCCCCC
BABAAAABCBCBCCCCCCCCCCCCCCCC
CCCCBBBCCCCCCCCCCCCCCCCCCCC
CCBCBBAABBBBBAACABCCACCCCCCCCC
AACBABACBBABABABACCCAACACBBBBBC
CCABABABAACCCABACCCCCCCCCCCCCA
AAAABACCBBCCCCBACCACCCCCCCCCDD
CCCBACBAABBCCCCCCCCCCCCCCCCC
ACBCACCCCCBBBBBAABAABAACBBCCCD
ABCBAACCBABACABABBCABABCCCCBBB
CCCBACCBCCCBBBCBCCCCCCCCCCCC
AAABABBCCCCCCCCBAABBBBCCCCCCCC
BACCBCBABBBABCAAACCCCAACABCCCC
BAAABBAABCBAACAABCCCCCCCCCCCC
CACBACCBAABABBCBCCCCBCCBBDDDD
AABCCCCAABCCCBCCCCCBABABAABABB
BAAABCCABAACCCCCCCCCBBBCCCCCD
CCCAAABBCBCCCCCCCCBCCCCCCCC
BCCBBABBBBCCCCCCCCBBBCCCCCCCC
BCBBBBAAACABCCBBAACBABABCCCCAAD
ABCCBCBABACCCCBABABAAAACCCCAA
CABCCACACCCCCBABAABABBBBBBBB
ABBCAABABACCABCABACCCCCCCCCDD
CCCBCCCBAAAAACCCBBCCCCCCCC
CBACBAAABCCCCBBBCCBCCB BBBBBD
ACCCBBCBBBCCBBBBBCCCCCCCCCCCC
BBCBCCBCCCCCCCCCCCCCCCCCCCC
BACCBACCCCCCCCCCCCCBBBCCCCCCCC
CCBACABAABBCBCCCCCCCCCCCCCCCC
CCBCBBAACCAACACCBABAAAABABBABB
CCBACBCCCCBBBACCBBCCBBBBBBDD
ABCCCCCBACAAAABBAABBBBBBBBBBB
BCCBABAACCBBBBCCCCCBCCCCCCCC
CBACCCCCBABAABCCCBCCBCCCBCCCC
CBCCBCCBBBCCCCBCCCCCCCCCCCC
ABBBABAACCCCCCCCCCCCCCCCCCCCC
ABBAABABAACCBABCABACCBBBCCBBB

ABBBBACCCCABAABACCCCCCCCCCCCCC
CCCB BBBBAACCBAAACCCCCCCCCCCCCDD
BAABACBACBACBAACCCBCABACCCBCCC
ABABBABBCCCCCCCCBBBACBACBBBBBBD
BCCCCCBBCBBBBCCCBCCBCCCCCCCCC